



KO'P O'ZGARUVCHILI FUNKSIYA UCHUN SILVESTR ALOMATINING BA'ZI TADBIQLARI

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Annotasiya. Ushbu maqolada ko'p o'zgaruvchili funsiya uchun Silvestr alomatining ba'zi tadbiqlarining isbotlari keltirilgan. Silvestr alomatining amaliy tadbiqlari sifatida bir nechta misollar yechib ko'rsatilgan.

Kalit so'zlar: Silvestr alomati, minimum, maksimum, uzluksizlik, xususiy hosila, kvadratik forma, koeffitsent, ekstremumning yetarli sharti.

Abstract. This paper provides rigorous proofs of several applications of Sylvester's criterion in the context of multivariable functions. To illustrate its practical utility, a number of representative examples are solved and discussed.

Keywords: Sylvester's criterion, minimum, maximum, continuity, partial derivative, quadratic form, coefficient, sufficient condition for an extremum.

Аннотация. В данной статье приведены строгие доказательства ряда приложений критерия Сильвестра в контексте функций многих переменных. Для демонстрации его практической полезности рассмотрены и решены несколько показательных примеров.

Ключевые слова: как критерий Сильвестра, минимум, максимум, непрерывность, частные производные, квадратичные формы, коэффициенты, а также достаточные условия существования экстремума.

1-ta'rif. n ta x_1, x_2, \dots, x_n noma'lumlarning $f(x)$ kvadratik formasi deb har bir hadi bu no'malumlarining kvadrati yoki ikkita noma'lumning ko'paytmasidan iborat bo'lgan

$$f = \sum_{i=1}^n \sum_{j=1}^n a_{ij} x_i x_j \quad (1)$$



yig'indiga aytiladi.

Kvadratlik formaning a_{ij} koeffitsiyentlaridan

$$A = \begin{pmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \dots & \dots & \dots & \dots \\ a_{n1} & a_{n2} & \dots & a_{nn} \end{pmatrix}$$

kvadrat matritsani tuzish mumkin. Bu yerda A matritsaning barcha xarakteristik ildizlari haqiqiy bo'lishi uchun $a_{ij} = a_{ji}$ deb faraz qilinadi. A matritsaning rangi (1) kvadratlik formaning rangi deyiladi. A matritsa aynimagan bo'lsa, (1) kvadratlik forma xosmas deyiladi.

Kvadratlik formaning koeffitsiyentlari haqiqiy yoki kompleks sonlar bo'lishiga bog'liq holda, kvadratlik forma haqiqiy yoki kompleks deyiladi.

Bizga ushbu

$$P(\xi_1, \xi_2, \xi_3, \dots, \xi_m) = \sum_{i,k=1}^m a_{ik} \xi_i \cdot \xi_k$$

Kvadratlik forma berilgan bo'lsin va uning musbat aniqlangan bo'lishi uchun

$$a_{11} > 0, \begin{vmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{vmatrix} > 0, \begin{vmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \dots & \dots & \dots & \dots \\ a_{m1} & a_{m2} & \dots & a_{mn} \end{vmatrix} > 0$$

tengsizliklarning, manfiy aniqlangan bo'lishi uchun esa

$$a_{11} < 0, \begin{vmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{vmatrix} > 0, \dots, (-1)^m \begin{vmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \dots & \dots & \dots & \dots \\ a_{m1} & a_{m2} & \dots & a_{mn} \end{vmatrix} > 0$$

tengsizliklarning bajarilishi zarur va yetarli.

Xususiyl holni funktsiya ikki o'zgaruvchiga bog'liq bo'lgan holni qaraylik.

$f(x_1, x_2)$ funktsiya $x^0 = (x_1^0, x_2^0)$ nuqtaning biror atrofi

$$U_\delta(x^0) = \{x = (x_1, x_2) \in R^2: \rho(x, x^0) < \delta\} \quad (\delta > 0)$$

da birinchi, ikkinchi tartibli uzluksiz hosilalarga ega bo'lib, x^0 esa qaralayotgan funktsiyaning statsionar nuqtasi bo'lsin:

$$f'_{x_1}(x^0) = 0, \quad f''_{x_2}(x^0) = 0,$$



Odatdagidek, $a_{11} = f'_{x_1^2}(x^0)$, $a_{12} = f''_{x_1x_2}(x^0)$, $a_{22} = f'_{x_2^2}(x^0)$

1) Agar

$\begin{vmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{vmatrix} = a_{11}a_{22} - a_{12}^2 > 0$ va $a_{11} > 0$ bo'lsa, $f(x)$ funksiya x^0 nuqtada minimumga erishadi.

2) Agar

$a_{11}a_{22} - a_{12}^2 > 0$ va $a_{11} < 0$

bo'lsa, $f(x)$ funksiya x^0 nuqtada maksimumga erishadi.

3) Agar $a_{11}a_{22} - a_{12}^2 < 0$ bo'lsa, $f(x)$ funksiya x^0 nuqtada ekstremumga erishmaydi.

4) Agar $a_{11}a_{22} - a_{12}^2 = 0$ bo'lsa, $f(x)$ funksiya x^0 nuqtada ekstremumga erishishi mumkin, erishmasligi ham mumkin.

Haqiqatan ham 1) va 2)- hollarda kvadratik forma mos ravishda musbat aniqlangan yoki manfiy aniqlangan bo'ladi. (Silvestor alomati)

3)- holda, ya'ni

$$a_{11}a_{22} - a_{12}^2 < 0 \quad (2)$$

bo'lganda $Q(\xi_1, \xi_2) = a_{11}\xi_1^2 + 2a_{12}\xi_1\xi_2 + a_{22}\xi_2^2$ kvadratik forma noaniq bo'ladi. Shuni isbotlaylik.

$a_{11} = 0$ bo'lsin. Bu holda (2) dan $a_{12} \neq 0$ bo'lishi kelib chiqadi. Natijada $Q(\xi_1, \xi_2)$ kvadratik forma ushbu

$$Q(\xi_1, \xi_2) = (2a_{12}\xi_1 + a_{22}\xi_2)\xi_2$$

ko'rinishga keladi. Bu kvadratik forma

$$\xi_1 = \frac{1 - a_{22}}{2a_{12}}, \quad \xi_2 = 1$$

qiymatda musbat:

$$Q\left(\frac{1-a_{22}}{2a_{12}}, 1\right) = 1 > 0 \quad \text{va} \quad \xi_1 = \frac{1+a_{22}}{2a_{12}} \quad \xi_2 = -1$$

Qiymatda esa manfiy:



$$Q\left(\frac{1+a_{22}}{2a_{12}}, -1\right) = -1 < 0$$

bo'ladi.

Shunday qilib, $a_{11}a_{22} - a_{12}^2 < 0$ bo'lganda $Q(\xi_1, \xi_2)$ kvadratik formaning noaniq bo'lishi isbot etildi.

4) – holni, ya'ni $a_{11}a_{22} - a_{12}^2 = 0$ bo'lgan holni qaraylik. Bu holda $a_{11} = 0$ bo'lsa, unda $a_{12} = 0$ bo'lib, $Q(\xi_1, \xi_2)$ kvadratik forma ushbu

$$Q(\xi_1, \xi_2) = a_{22}\xi_2^2$$

ko'rinishini oladi.

Ravshanki, $a_{22} > 0$ bo'lganda $Q(\xi_1, \xi_2) \geq 0$,

$$a_{22} < 0 \text{ bo'lganda } Q(\xi_1, \xi_2) \leq 0$$

bo'lib, ξ_1 ning ixtiyoriy qiymatida $Q(\xi_1, 0) = 0$ bo'ladi.

Agar $a_{11} > 0$ bo'lsa, $Q(\xi_1, \xi_2) = a_{11}\left(\xi_1 + \frac{a_{12}}{a_{11}}\xi_2\right)^2 \leq 0$,

$a_{11} < 0$ bo'lganda $Q(\xi_1, \xi_2) = a_{11}\left(\xi_1 + \frac{a_{12}}{a_{11}}\xi_2\right)^2 \leq 0$,

bo'lib, ξ_1 va ξ_2 larning

$$\xi_1 = -\frac{a_{12}}{a_{11}}\xi_2$$

tenglikni qanoatlantiruvchi barcha qiymatlarida $Q(\xi_1, \xi_2)$ kvadratik forma nolga teng bo'ladi. Demak, qaralayotgan holda $Q(\xi_1, \xi_2)$ kvadratik forma yarimmusbat aniqlangan yoki yarimmanfiy aniqlangan bo'ladi.

$$u_1(x) + u_1(y) = \sum_{i=1}^3 (1 - \cos x_i) + \sum_{i=1}^3 (1 - \cos y_i) = 6 - \cos x_1 - \cos x_2 - \cos x_3 - \cos y_1 - \cos y_2 - \cos y_3$$

$$\frac{\partial u_1(x)}{\partial x_1} = \sin x_1, \quad \frac{\partial u_1^2(x)}{\partial x_1 \partial x_2} = 0, \quad \frac{\partial u_1(x)}{\partial x_1 \partial x_1} = \cos x_1$$

$$\frac{\partial u_1(x)}{\partial x_i \partial x_j} = \begin{cases} \cos x_i, & i = j \\ 0 & i \neq j \end{cases}$$



$$\frac{\partial u_1(x)}{\partial y_i \partial y_j} = \begin{cases} \cos y_i, & i = j \\ 0 & i \neq j \end{cases}$$

$$A = \begin{pmatrix} \frac{\partial u^2(x)}{\partial x_1 \partial x_1} & \frac{\partial u^2(x)}{\partial x_1 \partial x_2} & \frac{\partial u^2(x)}{\partial x_1 \partial x_3} & \frac{\partial u^2(x)}{\partial x_1 \partial y_1} & \frac{\partial u^2(x)}{\partial x_1 \partial y_2} & \frac{\partial u^2(x)}{\partial x_1 \partial y_3} \\ \frac{\partial u^2(x)}{\partial x_2 \partial x_1} & \frac{\partial u^2(x)}{\partial x_2 \partial x_2} & \frac{\partial u^2(x)}{\partial x_2 \partial x_3} & \frac{\partial u^2(x)}{\partial x_2 \partial y_1} & \frac{\partial u^2(x)}{\partial x_2 \partial y_2} & \frac{\partial u^2(x)}{\partial x_2 \partial y_3} \\ \frac{\partial u^2(x)}{\partial x_3 \partial x_1} & \frac{\partial u^2(x)}{\partial x_3 \partial x_2} & \frac{\partial u^2(x)}{\partial x_3 \partial x_3} & \frac{\partial u^2(x)}{\partial x_3 \partial y_1} & \frac{\partial u^2(x)}{\partial x_3 \partial y_2} & \frac{\partial u^2(x)}{\partial x_3 \partial y_3} \\ \frac{\partial u^2(x)}{\partial y_1 \partial x_1} & \frac{\partial u^2(x)}{\partial y_1 \partial x_2} & \frac{\partial u^2(x)}{\partial y_1 \partial x_3} & \frac{\partial u^2(x)}{\partial y_1 \partial y_1} & \frac{\partial u^2(x)}{\partial y_1 \partial y_2} & \frac{\partial u^2(x)}{\partial y_1 \partial y_3} \\ \frac{\partial u^2(x)}{\partial y_2 \partial x_1} & \frac{\partial u^2(x)}{\partial y_2 \partial x_2} & \frac{\partial u^2(x)}{\partial y_2 \partial x_3} & \frac{\partial u^2(x)}{\partial y_2 \partial y_1} & \frac{\partial u^2(x)}{\partial y_2 \partial y_2} & \frac{\partial u^2(x)}{\partial y_2 \partial y_3} \\ \frac{\partial u^2(x)}{\partial y_3 \partial x_1} & \frac{\partial u^2(x)}{\partial y_3 \partial x_2} & \frac{\partial u^2(x)}{\partial y_3 \partial x_3} & \frac{\partial u^2(x)}{\partial y_3 \partial y_1} & \frac{\partial u^2(x)}{\partial y_3 \partial y_2} & \frac{\partial u^2(x)}{\partial y_3 \partial y_3} \end{pmatrix}$$

$$A = \begin{pmatrix} \cos x_1 & 0 & 0 & 0 & 0 & 0 \\ 0 & \cos x_2 & 0 & 0 & 0 & 0 \\ 0 & 0 & \cos x_3 & 0 & 0 & 0 \\ 0 & 0 & 0 & \cos y_1 & 0 & 0 \\ 0 & 0 & 0 & 0 & \cos y_2 & 0 \\ 0 & 0 & 0 & 0 & 0 & \cos y_3 \end{pmatrix}$$

I hol. $x = (0,0,0)$ va $y = (0,0,0)$

$$A = \begin{pmatrix} 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 \end{pmatrix}$$

$$A_1 = 1$$

$$A_2 = \begin{vmatrix} 1 & 0 \\ 0 & 1 \end{vmatrix} = 1 > 0 \quad A_3 = \begin{vmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{vmatrix} = 1 > 0$$



$$A_4 = \begin{vmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{vmatrix} = 1 > 0$$

$$A_5 = \begin{vmatrix} 1 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 1 \end{vmatrix} = 1 > 0$$

$$A_6 = \begin{vmatrix} 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 \end{vmatrix} = 1 > 0$$

A matritsaning barcha bosh minorlarining determinantlari musbat bo'lganligi uchun musbat aniqlangan bo'ladi.

II hol. $x = (\pi, \pi, \pi), y = (\pi, \pi, \pi)$

$$A = \begin{pmatrix} -1 & 0 & 0 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 & 0 & 0 \\ 0 & 0 & -1 & 0 & 0 & 0 \\ 0 & 0 & 0 & -1 & 0 & 0 \\ 0 & 0 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & 0 & 0 & -1 \end{pmatrix}$$

$$A_1 = -1 < 0$$

$$A_2 = \begin{vmatrix} -1 & 0 \\ 0 & -1 \end{vmatrix} = 1 > 0 \quad A_3 = \begin{vmatrix} -1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & -1 \end{vmatrix} = -1 < 0$$

$$A_4 = \begin{vmatrix} -1 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 \\ 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 \end{vmatrix} = 1 > 0$$

$$A_5 = \begin{vmatrix} -1 & 0 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 & 0 \\ 0 & 0 & -1 & 0 & 0 \\ 0 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & 0 & -1 \end{vmatrix} = -1 < 0$$



$$A_6 = \begin{vmatrix} -1 & 0 & 0 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 & 0 & 0 \\ 0 & 0 & -1 & 0 & 0 & 0 \\ 0 & 0 & 0 & -1 & 0 & 0 \\ 0 & 0 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & 0 & 0 & -1 \end{vmatrix} = 1 > 0$$

Bunda bosh minorlar ning barchasi musbat emas. Demak bu matritsa musbat aniqlanmagan.

$$\text{III hol. } x = (0, \pi, 0) \quad y = (0, \pi, 0)$$

$$A = \begin{pmatrix} 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 \end{pmatrix}$$

$$A_1 = 1$$

$$A_2 = \begin{vmatrix} 1 & 0 \\ 0 & -1 \end{vmatrix} = -1 < 0 \quad A_3 = \begin{vmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 1 \end{vmatrix} = -1 < 0$$

$$A_4 = \begin{vmatrix} 1 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{vmatrix} = -1 < 0$$

$$A_5 = \begin{vmatrix} 1 & 0 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & 0 & 1 \end{vmatrix} = 1 > 0$$

$$A_6 = \begin{vmatrix} 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 \end{vmatrix} = 1 > 0$$

Bu holda ham matritsa musbat aniqlanmagan.

$$\text{IV hol. } x = (0, \pi, 0) \quad y = (\pi, 0, 0)$$



$$A = \begin{pmatrix} 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & -1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 \end{pmatrix}$$

$$A_1 = 1$$

$$A_2 = \begin{vmatrix} 1 & 0 \\ 0 & -1 \end{vmatrix} = -1 < 0 \quad A_3 = \begin{vmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 1 \end{vmatrix} = -1 < 0$$

$$A_4 = \begin{vmatrix} 1 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & -1 \end{vmatrix} = 1 > 0$$

$$A_5 = \begin{vmatrix} 1 & 0 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & 0 & 1 \end{vmatrix} = 1 > 0$$

$$A_6 = \begin{vmatrix} 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & -1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 \end{vmatrix} = 1 > 0$$

Bu holda ham matritsa musbat aniqlanmagan.

Xulosa: Ushbu maqolada ko'p o'zgaruvchili funsiya uchun Silvestr alomatining ba'zi tadbirlarining isbotlari keltirilgan hamda Silvestr alomatining amaliy tadbirlari sifatida bir nechta misollar yechib ko'rsatilgan.

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